MCRT[®] 88700V Series Bearingless

Dual-Range Digital Torquemeters

High Ranges: 500 to 4,000,000 lbf-in (56.5 Nm to 452 kNm), Low Ranges: 100 to 800,000 lbf-in (11.3 Nm to 90.4 kNm)

Best Performance under Real - World Conditions Industries Highest Overrange and Overload World Class Temperature Performance Greatest Immunity to External Noise Accredited*, CW and CCW Dead Weight Cal **Bipolar Rotor Shunt Cal** Simple, Non-critical Installation • 0.05% Accuracy*; 21,000 Samples/Sec. • \geq 300% and \geq 150% Overrange • 1,000% and 200% Overload • 0.0006%/°F Temperature Compensation • FM Output • ±5.000/±10.000V Analog Output RS232, RS422, RS485 Com Ports - Software Included · Works With VFD's, ISM Transmitters and Other Industrial Noise Sources • 48µS Max/Min Acquisition, 10 Bessel Data Filters, Tare Function, Rotor Temperature Measurement, Speed Pickup Option * NIST traceable calibrations are performed in our accredited laboratory (NVLAP Lab Code 200487-0). For details visit our website or follow the accreditation link at www.nist.gov

MCRT[®] 88700V's measure high and low torques without the cost and inconvenience of swapping two conventional sensors. They also correctly measure average torque when the peak to average torque ratio is high. Thus, avoiding the accuracy loss that occurs when an oversized sensor is used to prevent physical damage.

They have high accuracy in real-world applications, not just in the cal lab. That's due, in part, to industries highest Overrange. High overrange avoids clipping real-world torque peaks and driveline torsionals. Without high Overrange, clipped peaks produce large errors¹.

World class temperature performance greatly reduces drive heating and gradient errors and avoids Low Range accuracy degradation. Further enhancing real-world performance is very high stiffness and low deflection, exceptional 1. See Application Note 20805B for details. hardening to EMI from Variable Frequency Drives, other industrial noise sources and ISM devices see Bulletin 8700.

Each range is calibrated CW and CCW and documented by a NVLAP approved Calibration Certificate certifying NIST traceability and that our laboratory operation and quality management system meet ISO/IEC 17025:2005. A *bi-directional rotor shunt cal* verifies the entire CW and CCW data chains. It may be invoked from switches, I/O lines or your computer. You can select from ten units of measure without recalibration.

Included software interfaces Windows-based PC's. It displays and plots real time data, selects 5V or 10V output, torque range, filter cutoff frequency, FM center frequency, units of measure, calls calibration, tare, reset max/mins, saves data and test setups, etc.

S. HIMMELSTEIN AND COMPANY

Designing and Making the Worlds Best Torque Instruments Since 1960

Torque 🖝 Ibf-in	(default), lbf-ft, ozf-in, o	zf-ft, N-m, kN-m	۱, N-cm, kgf-m, kgf-cm, gf-cm	Temperature 🖝 🛛	F (default), °C
Order Number 🖝	MCRT [®] 88707V	(1 - 5)	С	0	В
	Model No. From Table	High Range	<u>Performance Code</u> N if Standard, C if Enhanced	<u>Speed Pickup Option</u> Z if magnetic, O if optical, N if none	Speed Rating Suffix, When Applicable H for High Speed, B for Lower Speed Omitted if not available
	An MCRT [®] 88707V(1-5)C0 Pickup, and a 6,000 rpm M	3 is a 100,000 lbf- laximum Speed Ra	in High Range Torquemeter with a 2 titing.	20,000 lbf-in Low Range, Enhancec	Performance, Installed Optical Speed

General Specifications	Standard, Code N Performance		Enhanced, Code C Performance			
	High Range	Low Range	High Range	Low Range		
Torque ¹ Combined Linearity & Hysteresis (% of Range)	<±0.1		≤±0.05			
Torque Nonrepeatability (% of Range)	≤±0.05	≤±0.07	≤±0.020	≤±0.05		
Zero Drift Torque (% of Range/°F)	≤±0.001	≤±0.005	≤±0.0006	≤±0.003		
Span Drift Torque (% of Reading/°F)	< ±0.002 < ± 0.001					
Temperature Ranges (°F)	Compensated: +75 to +175, Useable: - 25 to +185, Storage: - 65 to +225					
Rotor-to-Stator Maximum Misalignment (inch)	Axial: ±0.4, Radial:0.3 with or without Code O Optical Pickup; For MCRT® 88708V Series: ±0.25 Axial, 0.3 Radial; For MCRT® 88709V & 88710V Series: ±0.2 Axial, 0.2 Radial. If Code Z Magnetic Pickup is used, radial alignment must be held within ±0.020 and axial alignment within ±0.040.					
Analog Torque Output (Auto-Scaled):	CW ² : +10.000 volts or , + 5.000 volts - user selectable (default = +10.000 V). CCW ² - 10.000 volts or , = 5.000 volts - user selectable (default = , 10.000 V).					
Maximum Load	CCw -: - 10.000 voits or, - 5.000 voits - user selectable (default = - 10.000 v). >10 kΩ Resistive, <0.05 uF Capacitive					
Frequency Modulated Output (Auto-Scaled)	10±5 kHz, 20±10 kHz or 40±20 kHz; software changeable. TTL square wave format.					
Constant Delay Torque Signal Filters	Field selectable from 1 to 1,000 Hz in ten 1-2-5 steps plus 3 kHz using furnished software.					
Minimum Overrange ³ - Applies to All Outputs	${>}150\%$ of High Range and ${>}300\%$ of Low Range except Analog Output is limited to ${\pm}15V.$					
Output Noise, All Outputs (% of Range)	<0.01 at 1 Hz, <0.01 at 10 Hz, <0.015 at 100 Hz and < 0.05 at 1 kHz.					
System Response	Torque is sampled at 21 kHz. Analog output bandwidth is 3 kHz, reducible by filtering.					
System Resolution	High Range: Low Range:	: ≥0.01% on all outputs. Int ≥0.025% of range (≥0.005	ernal data resolution is 24 bits % of High Range) on all outputs	5.		
RS232, RS422, RS485 Com Port	Duplex port outputs Torque and Tempe	rature with units of measure	e. Inputs Range, filter selection	, ±5 or ±10V analog output,		
Interface Software	cais Provided. Interfa	cal, tare, clear tare, reset m ices with Windows based PC	ax/min, save data, etc. 2. Includes interconnect cable t	o PC.		
Baud Rate	115,200 Baud. Drivers are short circuit (current limit) and \pm 15 kV ESD protected. RS232 = 50 feet, RS422/485 = 4,000 feet; 120 ohm termination may be accessed via software.					
Rotor to Stator Data Transfer Pate	1.25 MBaud.					
	5 input and 2 output all user assignable. Input defaults are +CAL, - CAL. TARE, CLEAR TARE, TOGGLE RANGE, Output lines are					
I/O Lines (user definable)	FM Torque Out and Data OK.					
Bi-polar Rotor Shunt Cal Enable	From Stator Switches (one CW and one CCW), via I/O, or PC Com Port using furnished software.					
Range Select	Accomplished via Com Port (software supplied) and Toggle Range I/O Line.					
Range Indicator	The selected Range is output via the Com Port and displayed on the computer screen by the supplied software. Additionally, whenever the LOW Range is selected, the Data LED is periodically dimmed.					
Stator Keypad Control Switches	+ Cal invokes CW Rotor Shunt Cal, - Cal invokes CCW Rotor Shunt Cal, holding both for 5 seconds invokes TARE.					
Status LEDs (on Stator Keypad)	Power (Yellow = Power-up, Green = OK, Red = Fault); Data (Green = OK, Red = Data Error); Rotor Temperature (Green = In Operating Range, Red = Out of Operating Range).					
Rotor Temperature Measurement	Output via Com Port. Measurement range is 0 to 185 °F. Accuracy is ± 2 °F, nominal.					
Speed Pick Up Options	30 to 60 pulse/revolution (model dependent) Zero Velocity Speed Pickups. Code O specifies Optical Pickup. Code Z specifies Magnetic Pickup, which, if used, limits rotor-stator misalignment; see above.					
Supply Voltage/Power Input ⁴	10 to 26 VDC @ 6 W with rotor aligned to 10 W with maximum misalignment.					
Start-up Input Current	<2 A					

 Each torque range is factory calibrated and documented in the Calibration Certificates accompanying the Torquemeter. The Certificate also documents NIST traceability. Although the system allows setting any range less than the HIGH range, if it is a non-calibrated range you won't have either certified results or be assured of their accuracy.

- 2. CW torque causes the shaft to turn CW when viewed from its driven end. CCW torque causes the opposite rotation.
- 3. Data is linear to the Overrange specified. Caution: the Torquemeters have infinite fatigue life for full reversals equal to one half their Overload Rating or, their High Range torque rating. Knowingly operating above that value risks a fatigue failure. Fatigue is not an issue on the Low Range which can sustain a 1,000% Overload (of its range) without a failure.
- 4. Fused and reverse polarity protected.
- 5. All outputs are fused. Digital inputs are reverse polarity and overvoltage protected.
- 6. Specifications are subject to change without notice.

